

## APCO QUALITY AND EXPERIENCE

## **OUR COMPANY**

Established in Switzerland in 1992, APCO Technologies is a project-oriented company specialised in heavy machinery for the SPACE, ENERGY, and INDUSTRY sectors. To date, our company has known a continuous growth.





## **QUALITY FIRST**

Our success is notably due to our stringent quality policy at every scale of the projects your are entrusting us with.

Our strategy is defined as:

- Meeting your requirements, be formulated or not.
- Developing a strong corporate culture which allows our collaborators to work and thrive in the best conditions.
- Keeping a step ahead in terms of innovation

## **TEST EQUIPMENT**

Our experience in Mechanical Ground Support Equipment (MGSE) led us to develop specific test equipment such as positionners. Our first achievement was a vacuum positionner initially designed for ESA's Envisat instrument MERIS (Medium Resolution Imaging Spectrometer).

Today our MPMA (Mass Properties Measurement Adapter) has given good and loyal services at ESA's European Research and Techonolgy Center (ESTEC) for almost ten years.





## **Certifications**

esa **@esa** 

EN 9100: Quality Management Systems – Requirements for Aviation, Space and Defense Organizations ISO 9001: Quality Management **ISO 14001 :** Environmental Management **ISO 27001:** Information Security Management **OHSAS 18001:** Occupational Health and Safety Management Airbus DS IPCA +: Industrial Process Control Assessment

IXV (Intermediate eXperimental Vehicule) during its physical properties measurement campaign in ESTEC, Noordwijk

Source: European Space Agency

3 - APCO Technologies - Test Equipment

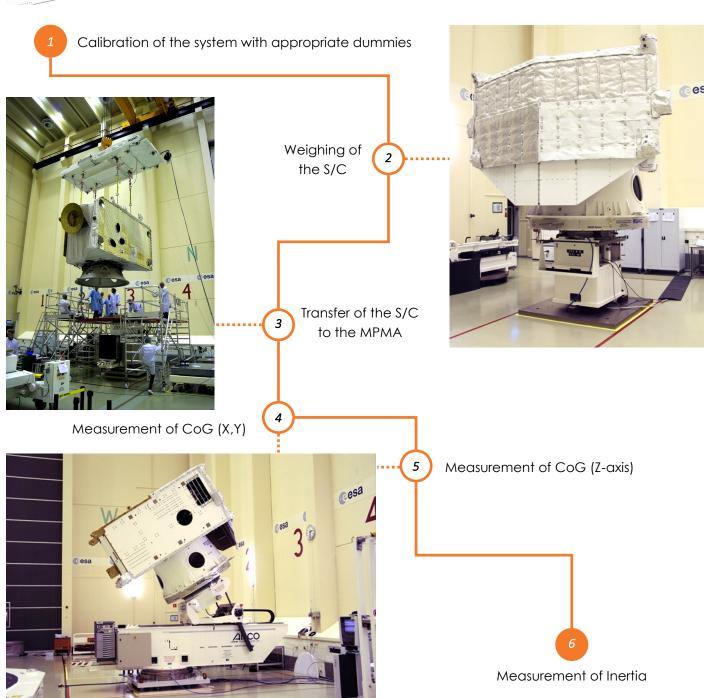
# MPMS FUNCTIONNING AND TEST SEQUENCE



### **PURPOSE**

The Mass Properties Measurement System (MPMS) is a complete system allowing the measurement and calculation of a spacecraft:

- Mass
- Center of Gravity (CoG) coordinates
- Moments of Inertia (Mol)
- Products of Inertia (Pol)

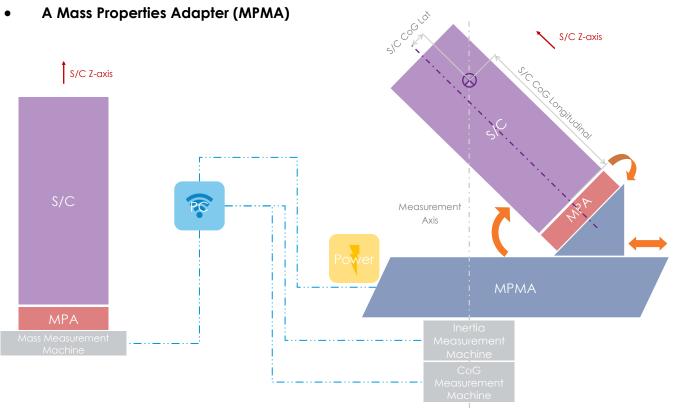


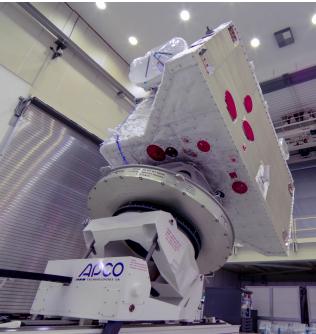
## MPMS FUNCTIONNING AND TEST SEQUENCE

### **COMPONENTS**

Several elements are needed to obtain the most accurate measurement in a reduced time, such as measurement machines, an automated positioning device, and a global software. The MPMS is composed of:

- A weighing machine
- A CoG position measurement machine
- An inertia measurement machine
- A Mass Properties Adapter (MPMA)
- A physical properties adapter to link the S/C to the MPMA (MPA)
- Mass dummy, calibrated masses and Mol calibration disks





## HERITAGE

The MPMA is a part of the MPMS measurement system in service in the « Hydra » clean room at the ESA European Space Research and Technology Center (ESTEC) in Noordwijk.

It is used in average in 3 to 4 campaigns per year. Recent campaigns include:

- IXV (eXperimental Test Vehicule)
- BepiColombo
- Metop-C
- Sentinel-2

BepiColombo in ESTEC, Noordwijk Source: European Space Agency

# MPMA CHARACTERISITICS

## MPMA TROLLEY

The translation trolley is composed of a frame interfacing with the main beam and a tilting frame supporting a crown ring on which the PPA is fitted.

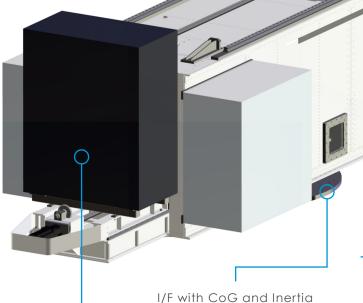
The purpose of this assembly is to ensure that the S/C CoG stays on the measurement axis while measuring S/C inertia. To achieve this, the frame translates automatically to adjust the position. Tilting is necessary to create the CoG offset with respect with the measurement axis to gain maximum precision.

S/C Interface

#### **BALLAST**

POWER -

The purpose of the ballast is to compensate the cantilever due to the main beam, the translation trolley and the specific physical properties adaptor in such a way than the measurements machines only « see » the S/C.



measurement machines

All MPMA movements are powered by an Uninterruptible Power Supply (UPS) and controlled from a remote computer by wireless connection.

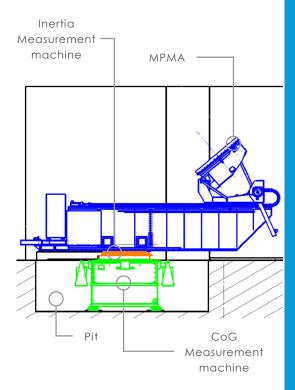
## SYSTEM SENSIBILITY

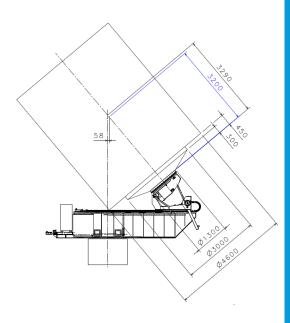
In order to obtain high accuracy results, the measurement system is extremely sensible.

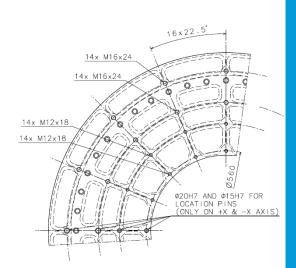
Main Beam

To ensure accuracy goals, all parts of the MPMA are designed to procure maximum rigidity, manufactured with great care and are preloaded if applicable.

Possible disturbances from the system itself or the environment (like air conditioning) must be eliminated or at least reduced to a minimum during measurement phases.







Characteristics			
Maximum Dimensions (LxWxH)	0°	5774 x 164	40 x 1885 mm
	40°	5915 x 164	10 x 2643 mm
Mass		31	00 Kg
Motion Mode	Electrical / manual (powerless mode)		
Motion Control	Wireless connection		
Power Supply	On battery during test phases		
Trolley Movements	Tilting	Rotation	Translation
- Range	0 - 40°	360°	Depending on CoG position
- Precision	± 0.1°	± 0.2°	± 0.1 mm
Facility Handling (for installation)			Crane
Environment Specifications			ISO 8

# S/C Limits

Max Envelop Dimension (Ø)	4610 mm		
Max S/C Mass	5000 Kg		
Manu S / C C o C o a si <sup>tt</sup> i a o	Longitudinal	3200 mm	
Max S/C CoG position	Lateral	75 mm	
May S/C Inartia	Longitudinal	4000 m²kg	
Max S/C Inertia	Lateral	10000 m <sup>2</sup> kg	

# Interfaces

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S/C	- 14 x M12 on a Ø560 mm + centering holes
(through	- 14 x M12 on a Ø750 mm + centering holes
specific properties	- 14 x M16 on a Ø900 mm + centering holes
adapter)	- 14 x M16 on a Ø1120mm + centering holes
Inertia measurement system	Depending on chosen measurement machines

## Contact us

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